



DEPARTMENT OF DEPARTMENT OF ELECTRICAL AND
ELECTRONICS ENGINEERING

COURSE PLAN – PART I			
Name of the programme and specialization	B.TECH. AND ELECTRICAL AND ELECTRONICS ENGINEERING		
Course Title	SOLID STATE DRIVES		
Course Code	EEPE27	No. of Credits	3
Course Code of Pre-requisite subject(s)	EEPC15, EEPC19		
Session	July 2020	Section (if, applicable)	---
Name of Faculty	Dr PINKYMOL K.P.	Department	ELECTRICAL AND ELECTRONICS ENGINEERING
Official Email	pinkymol@nitt.edu	Telephone No.	9526710598
Name of Course Coordinator(s) (if, applicable)			
Official E-mail		Telephone No.	
Course Type (please tick appropriately)	<input type="checkbox"/> Core course	<input checked="" type="checkbox"/> Elective course	
Syllabus (approved in BoS)			
<p>Introduction to solid state drives, various components – power converters, motors, loads, coupling mechanisms – Stability of drive.</p> <p>Modeling of DC motor drives – Transfer function and state-space models - Experimental determination of drive parameters – Speed control using AC to DC converters- Input performance parameters, Speed reversal schemes.</p> <p>Chopper fed DC motor drives – Four quadrant operation, Input filters design – Dynamic braking with DC chopper - Type-C chopper fed regenerative braking - Operation with non-receptive lines.</p> <p>Power converters for induction motor speed control - Harmonic behavior of induction motors-harmonic currents and harmonic torques using per phase equivalent circuit – Stator voltage control schemes - Speed control of wound type motors.</p> <p>State-space modeling of induction motors – Voltage source-Inverter fed operation - Field oriented control schemes – Current source-inverter drives – Principle of vector control.</p>			
COURSE OBJECTIVES			
1. To understand the basic concept of DC and AC Drives.			



2. To understand the various control techniques involved with both DC and AC Drives.
3. To brief about the working principle of Special Electrical Drives.

MAPPING OF COs with POs

Course Outcomes	Programme Outcomes (PO) (Enter Numbers only)
1. Learn the fundamental concepts of power electronic converter fed DC and AC machines.	1, 2, 4, 8, 9, 10
2. Analyse the converter fed motor under different torque/speed conditions	1, 2, 4, 7, 8, 9, 10, 12
3. Design converter fed drives with existing/new control techniques	1, 2, 3, 4, 7, 8, 9, 10, 12,13

COURSE PLAN – PART II

COURSE OVERVIEW

Modern electrical drive systems are used in a large number of industrial and domestic applications like the transportation system, machine tools, fans, pumps, robots, supervised actuation. In these applications, control of drives covers controlling the starting, speed, braking of the electric drive systems. In this course basic components of an electric drive system including mechanical loads, motor, power converters and controllers will be discussed separately first and various components will be combined later to discuss the complete drive system. Students will be able to explain and analyse industrial motors and power electronics converters from drive perspective and understand why a particular motor and /or a converter is selected for a particular drive application.

In this course, Chapter 1 discusses modern electric drive components and dynamic relations applicable to all types of drives. Chapter 2 is on dc machines their operations, modeling and transfer functions and measurement of drive parameters. Chapter 3 deals with the chopper controlled dc motor drives and its modeling. Principle of operation of the four-quadrant chopper and regeneration analysis also introduced. Power converters for induction motor speed control is introduced in chapter 4. Stator voltage control schemes and speed control of wound rotor machines are also presented. Chapter 5 deals with state-space modeling of induction motor. VSI fed and CSI fed operations and various control strategies are explained.

COURSE TEACHING AND LEARNING ACTIVITIES

S.No.	Week/Contact Hours	Topic	Mode of Delivery
1	Week 1 2 Contact Hours 25 th August to 28 th August	<u>Unit 1</u> Introduction to solid state drives, various components – power converters, motors, loads	Online



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2	Week 2 3 Contact Hours 31 st August to 4 th September	coupling mechanisms – Stability of drive	Online
3	Week 3 3 Contact Hours 7 th September to 11 th September	Unit 2 Modeling of DC motor drives – Transfer function and state-space models – Experimental determination of drive parameters	Online
4	Week 4 3 Contact Hours 14 th September to 18 th September	Transfer function and state-space models – Experimental determination of drive parameters	Online
5	Week 5 3 Contact Hours 21 st September to 25 th September	Speed control using AC to DC converters- Input performance parameters, Speed reversal schemes.	Online
6	Week 6 2 Contact Hours 28 th September to 1 st October	Unit 3 Chopper fed DC motor drives – Four quadrant operation	Online
7	Week 7 3 Contact Hours 5 th October to 9 th October	Input filters design -Dynamic braking with DC chopper First assessment	Online
8	Week 8 3 Contact Hours 12 th October to 16 th October	Type-C chopper fed regenerative braking - Operation with non- receptive lines.	Online
9	Week 9 3 Contact Hours 19 th October to 23 rd October	Unit 4 Power converters for induction motor speed control - Harmonic behavior of induction motors-harmonic currents and harmonic torques using per phase equivalent circuit	Online
10	Week 10 2 Contact Hours 26 th October to 29 th October	Stator voltage control schemes Second assessment	Online
11	Week 11 3 Contact Hours 2 nd November to 6 th November	Speed control of wound type motors. Unit 5 State-space modeling of induction motors – Voltage source-Inverter fed operation	Online



12	Week 12 3 Contact Hours 9 th November to 13 th November	Voltage source-Inverter fed operation- Field oriented control schemes	Online
13	Week 13 3 Contact Hours 16 th November to 20 th November	Current source-inverter drives – Principle of vector control. Compensation Test	Online
14	24 th November to 11 th December	Final assessment	Online

COURSE ASSESSMENT METHODS (shall range from 4 to 6)

S.No.	Mode of Assessment	Week/Date	Duration	% Weightage
1	First assessment – First class test	Week 7 5 th October to 9 th October	One hour 15 minutes	20
2	Second assessment – Second class test	Week 10 26 th October to 29 th October	One hour 15 minutes	20
3	Assignment/ Surprise Test/ Attendance/ Seminar	Throughout Semester		30
CPA	Compensation Assessment*	Week 13 16 th November to 20 th November	One hour 15 minutes	20
4	Final Assessment *	24 th November to 11 th December	One and half hour	30

ESSENTIAL READINGS: Textbooks, Reference books, website address, journals, etc
Text Books:

1. P.C.Sen, 'Thyristor DC Drives' John Wiley & Sons Publishers, New York, 2008.
2. R. Krishnan, 'Electric Motor Drives - Modeling, Analysis, and Control', Pearson Education Publishers, 1st Edition, 2011.
3. B.K.Bose, 'Modern Power Electronics and AC Drives', Pearson Education Publications, 2nd Edition, 2005.

Reference Books:

1. G.K. Dubey, 'Fundamentals of Electrical Drives', Narosa Publishing House, 2nd Edition, 2008.
2. T. Wildi, 'Electrical Machines Drives and Power Systems', Pearson Education Publications, 6th Edition, 2013.
3. Mohamed A. El-Sharkawi, 'Fundamentals of Electric Drives', Brooks/Cole, 2000.

Useful web links:

1. <https://nptel.ac.in/courses/108/104/108104140/>



Guidelines

- a) The number of assessments for any theory course shall range from 4 to 6.
- b) Every theory course shall have a final assessment on the entire syllabus with at least 30% weightage.
- c) One compensation assessment for absentees in assessments (other than final assessment) is mandatory. Only genuine cases of absence shall be considered.
- d) The passing minimum shall be as per the regulations.

B.Tech. Admitted in				P.G.
2018	2017	2016	2015	
35% or (Class average/2) whichever is greater.		(Peak/3) or (Class Average/2) whichever is lower		40%

- e) Attendance policy and the policy on academic dishonesty & plagiarism by students are uniform for all the courses.
- f) Absolute grading policy shall be incorporated if the number of students per course is less than 10.
- g) Necessary care shall be taken to ensure that the course plan is reasonable and is objective.