DEPARTMENT OF INSTRUMENTATION & CONTROL ENGINEERING NATIONAL INSTITUTE OF TECHNOLOGY, TIRUCHIRAPPALLI

Course Tit	Course Title Modern Control Engineering									
Course Title		CI 653	Credits	3						
Course Code		Chemical Engineering	Faculty	Dr. Ramal	alyan Ayyagari					
Departine Dro roquis	Department chemical significance									
Other Course			Mobile No.	+9194439	23485					
Other Course			Email	rkalyn@n	itt.edu					
		PROGRAM CORE								
This is a course on state variable modelling, analysis, and control of dynamical systems. The										
annroach	approach at a graduate level is to illustrate the deployment of mathematical analysis and design									
techniques on a given model and interpret the results in terms of implications on the real,										
neurical s	techniques on a given model, and interpret the results in terms of a pre-									
physical systems. The focus would be to build up a meral any or generation, and a provide the second systems as well as nonlinear MIMO systems.										
LOURSE OBJECTIVES										
1. To introduce advanced methods and teeningues of intervelation.										
2 To int	raduce mat	bomatical modeling a	nalysis, and design of a	a larger cla	ss of systems in a					
Z. TO Int	d framowor			•						
COURSE		((0)	4							
COURSE	nort Lof th	course the student is	exposed to an appropr	iate moderi	r paradigm for the					
1. In	part for the	r scale multi-input-mult	ti-output systems.							
SU	udy of large	i scale multi niput mun	outcomos: 1 2 3	4 5 10 12						
Alignment with the Program Outcomes: 1, 2, 3, 4, 5, 10, 12										
, In	part II, the	student understands th	importance of matrix	k theory in (designing practical					
2. cc	ontrol system	ms.								
	Al	ignment with the Prog	ram Outcomes: 1, 2, 3,	4, 5, 10, 12						
In	part III, the	student is motivated to	study more general sy	stems and	their stability using					
3. Lyapunov's theory.										
Alignment with the Program Outcomes: 1, 2, 3, 4, 5, 10, 12										
	AI	ignment with the riog	for foodback controllor	in contra	st to feed-forward					
In	part IV, the student learns to design feedback controllers, in contrast to feed-forward									
ч. со	ontrollers o	introllers of classical control, with a good balance of intuiton and mathematical rigour.								
Alignment with the Program Outcomes: 1, 2, 3, 4, 5, 10, 12										
Ir	n part V, t	he student learns to i	mplement modern co	ntrol syste	ms using a digital					
5.	omputer in	purcer, the loop.								
Alignment with the Program Outcomes: 1, 2, 3, 4, 5, 10, 12										
COURSE TEACHING		Datas	Topic(s)		Mode of Delivery					
Classes		Dates	Introduction to the	course.						
1 - 6	Aug 7, 10,	17	Review of Signals & Si	(stems	Board					
			Dart I (State-snace Me	dels)	Board/PPT					
7-12 Aug 21, 24, 28 Part I (State-space Wodels) Bound, I				cution & Part I						
August 31: ASSESSMENT 1: 1 hour test for 25% weight, covering introduction of article										

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13 - 18	Sep 4, 7, 11	Part II (An	Part II (Analysis of State Eqns)						
19 - 24	Sep 14, 18, 21	Part III (Ly	apunov Theory)	Board/PPT					
September 25: ASSESSMENT 2: 1 hour test for 20% weight, covering Parts II & III									
25 - 34	Oct 5, 9, 12, 23, 26	Part IV (Co	ontroller Design)	Board/PPT					
October 30: ASSESSMENT 3: 1 hour test for 20% weight, covering Part IV									
35 – 40	Nov 2, 6, 9,	Part V (Dig	Part V (Digital Control)						
November 23: ASSESSMENT 4: 2 hour test for 40% weight, covering all parts									
A detailed course calendar is attached herewith.									
COURSE ASSESSMENT METHODS									
S.No.	Mode of Assessment	Date	Duration	% Weightage					
1-3	3 AssessmentsAug 31,@ 20% weightageSept 25,60 minutes eachOct 30Oct 30		60%						
4	Compensatory Assessment	Nov 20	60 minutes	15%					
5	ind-term Assessment Nov 23 120 minutes		40%						
6	Re-assessment Covering the entire syllabus	Nov 27	180 minutes	100%					

 Evaluation will be completed by Nov 25 to facilitate Re-assessment on Nov 27 for students scoring < 35%.

• Students can access their answer scripts, for the unlikely event of re-grading, on Nov 25

RESULTS WILL BE SUBMITTED TO THE PAC ON November 30, 2017

ESSENTIAL READINGS:

- 1. Brogan, W.L., Modern Control Theory, 3/e, Prentice Hall, 1990
- 2. Hespanha, J.P., Linear Systems Theory, Princeton Univ. Press, 2009
- 3. Sontag, E.D., Mathematical Control Theory, 2/e, Springer Verlag, 2014

COURSE EXIT SURVEY

Feedback from the students during the class committee meetings

Feedback before End-term examination through a questionnaire, for improvements in future. COURSE POLICY (including attendance, grading, academic honesty, etc.)

ATTENDANCE

- 100% attendance, as on **November 6, 2017**, is mandatory, with an exemption up to 20% on genuine grounds; prior information and approval from the instructor is compulsory.
 - The only option for students with attendance < 80% is RE-DO. Please refer to the official rules for more details.

ASSESSMENTS AND GRADING POLICY

- A student can be, upon prior approval, absent from only one out of the the continuous assessments 1 3, for which he/she is allowed to take the compensatory assessment on November 20, 2017. Please note that compensatory assessment is not offered as an improvement test for everyone.
- A student is declared pass upon accumulating a minimum of 35% over all the 4 assessments; grading is done for those students declared passed based on the class average average and above shall get S, A, and B grades, and below average shall get C, D, and E.

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- In case one or more students fail to accumulate the stipulated minimum 35% (at the end of 4 assessments), they are permitted to take a one-time re-assessment for 100%; this is a 3-hour written examination on November 27, 2017, covering the entire syllabus.
- ACADEMIC HONESTY
- Mid-term and End-term assessments in this course must be strictly individual work.
- However, collaboration by individuals is encouraged at the level of ideas.
 - Feel free to ask each other questions, or brainstorm on solutions, or work together on a board. However, be careful about copying the actual solution. This sort of collaboration at the level of artifacts is permitted if explicitly acknowledged, but this is usually self-defeating.
- The principle behind the collaboration rule is simple:
 - \circ I want you to learn as much as possible; you may learn from me or from each other.
 - The goal of artifacts (programs) is simply to demonstrate what you have learned. So, I'm happy to have you share ideas, but if you want your own points you have to internalize the ideas and then craft them into an artifact by yourself, without any direct assistance from anyone else, and without relying on any idea taken from others (whether at this institute or from the web).

ACADEMIC DISHONESTY

For purposes of this class, academic dishonesty is defined as:

- Any attempt to pass off work on a test that didn't come straight out of your own head.
- Any collaboration on artifacts in which the collaborating parties do not clearly explain exactly who did what, at turn-in time.
- Any activity that has the effect of significantly impairing the ability of another student to learn. Examples here might include destroying the work of others, interfering with their access to resources, or deliberately providing them with misleading information.

ADDITIONAL COURSE INFORMATION

All the students are urged to be interactive during the classes. Further, the students are suggested to make a google group for faster dissemination of PPTs, discussions etc. They are free to interact with me over email any time, and if needed meet me in person with prior appointment.

Any changes in the proposed layout of the semester, due to unavoidable circumstances, shall be intimated immediately to the students and to the Chairperson, PAC

FOR SENATE'S CONSIDERATION

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Course Faculty Dr. Ramakalyan Ayyagari

CC-Chairpersol Dr. M. Perumalsamy

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HOD Dr. P. Sivashanmugam